



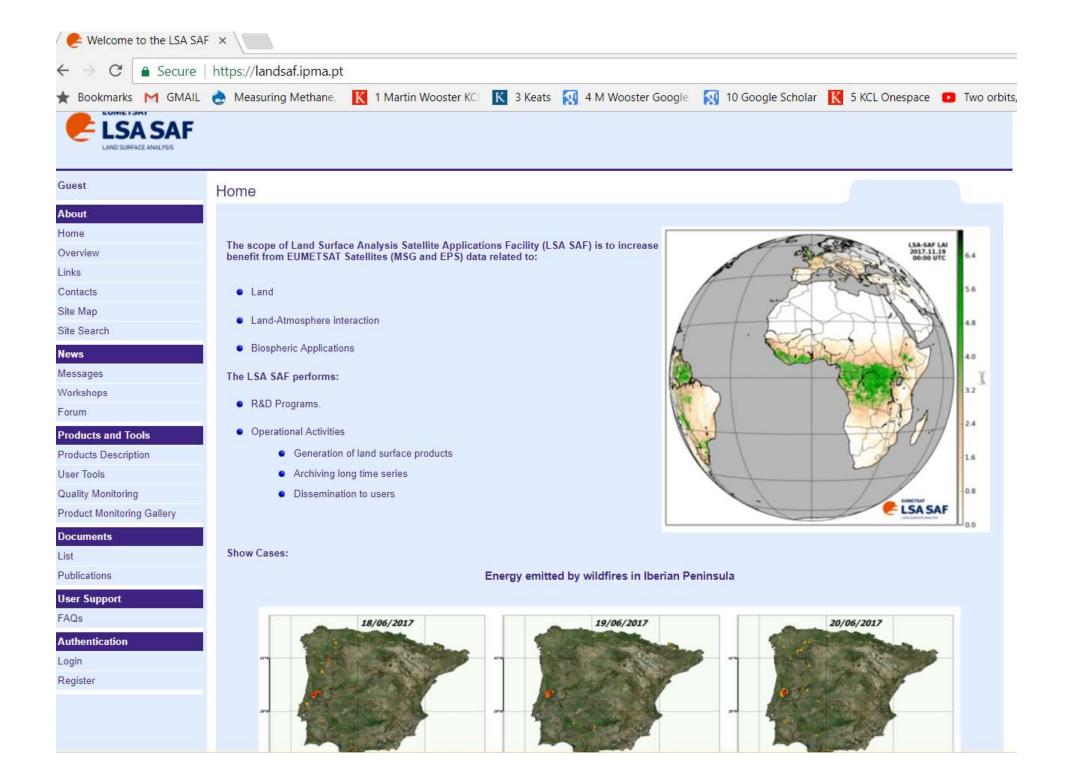
European Developments : -Meteosat & SLSTR



Martin J. Wooster, Weidong Xu, Jiangping He, Daniel Fischer, Tadas Nikonovas and Garth Roberts, Johannes Kaiser

Department of Geography, King's College London. NERC National Centre for Earth Observation (NCEO) Department of Geography, University of Southampton. European Geostationary Active Fire Products

> Recoded into Python
> Similar Code & Harmonised Formats Across Geo-Platforms 2





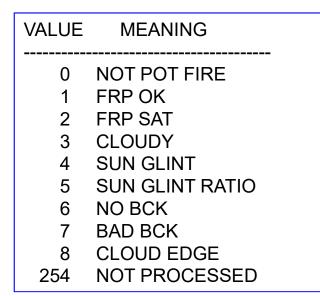


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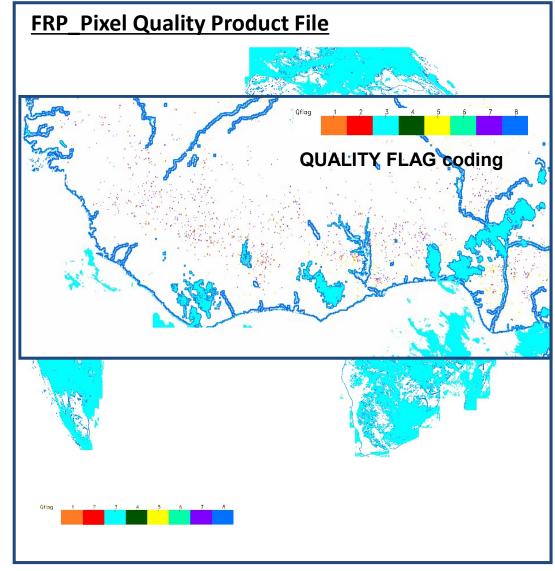
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Two HDF files for each slot

• "List Product"- Fire Data only

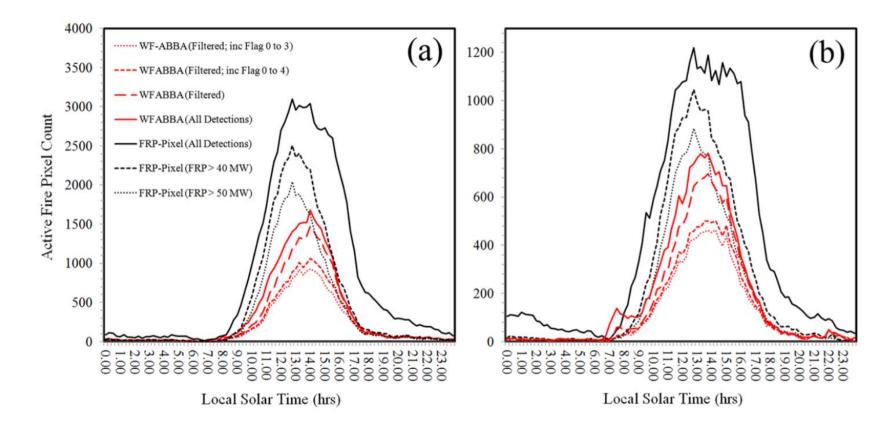


LSA SAF Meteosat FRP products-Part 1 : Algorithms, product contents, and analysis. / Wooster, M. J.; Roberts, G.; Freeborn, P. H.; Xu, W.; et al. In: Atmospheric Chemistry and Physics, Vol. 15, No. 22, 30.11.2015, p. 13217-13239.







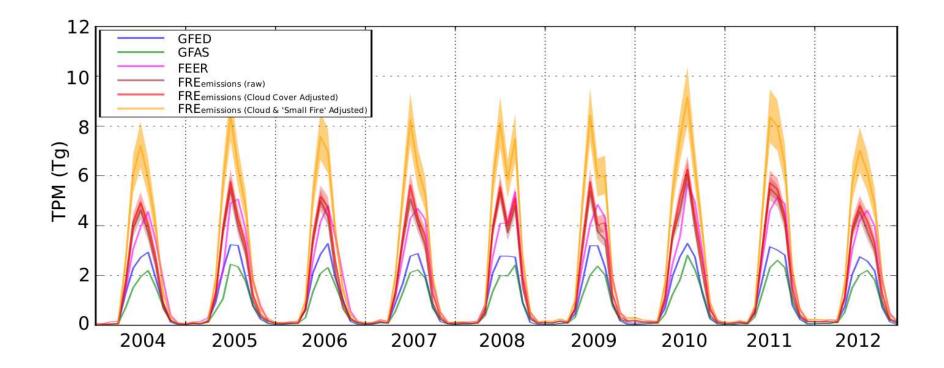


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Reprocessed to 2012 – now being extended to present day....

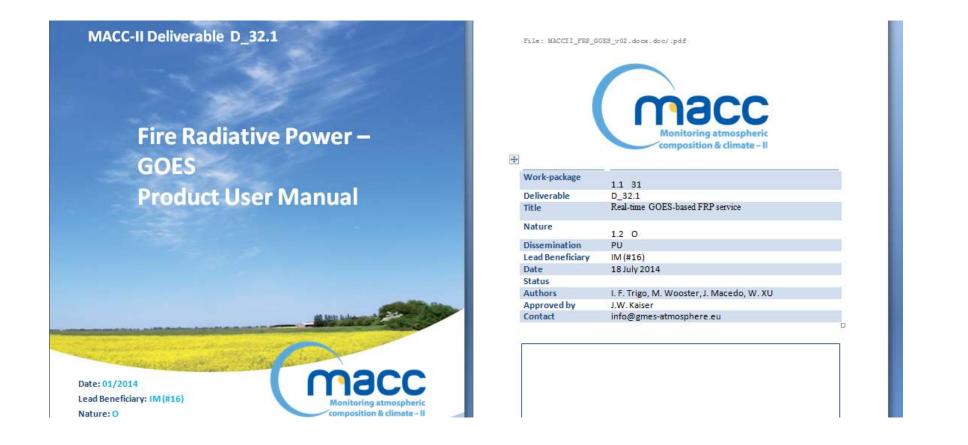


Direct Emissions Estimation - Mota and Wooster (2016) in review

GOES FRP Product (America's)



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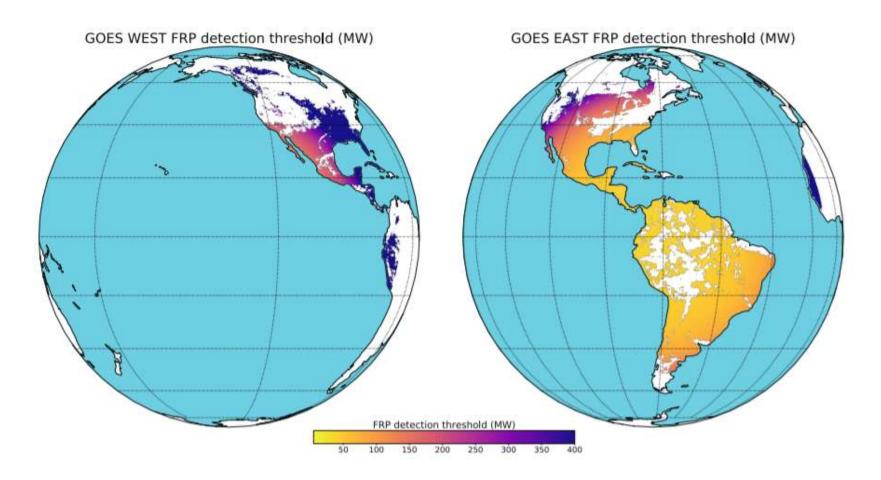
Produced using the same Fire Thermal Anomaly (FTA) as the LSA SAF Meteosat FRP

ftp://frp_public:frp@geoland2.meteo.pt

Harmonisation of Data (GFAS)



- University of London
- Synergistic use of polar-orbiting & geostationary FRP products.
- Polar-orbiting sensors detect smaller and less intense fires.
- But geostationary sensors provide near-continuous record.



METEOSAT 3rd GENERATION ~ 2020 or 2021

MTG FLEXIBLE COMBINED IMAGER



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- Full Disk Scan (FDS), with a basic repeat cycle of 10 mins.
- European Regional-Rapid-Scan (RRS) with a repeat cycle of 2.5 mins.

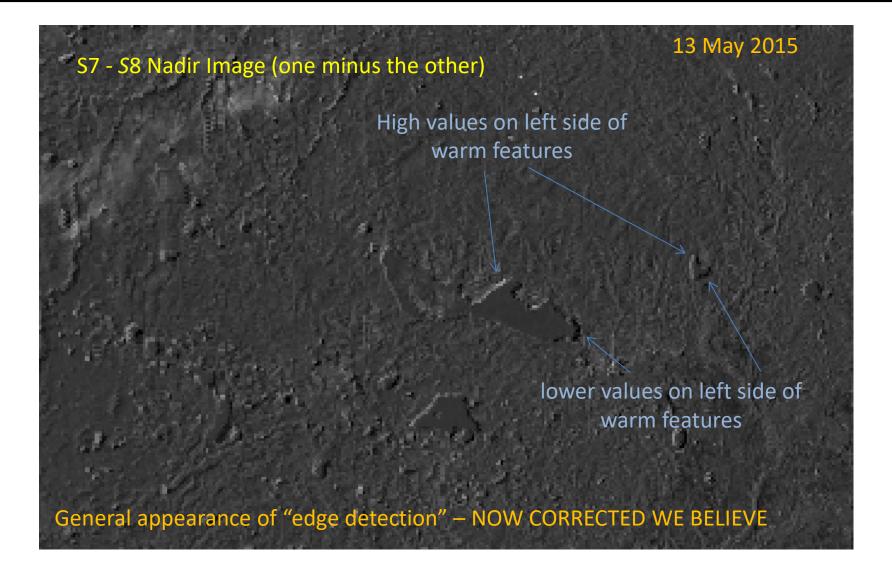
▼ Details				
CHANNEL	CENTRE WAVELENGTH, Δ0	SPECTRAL WIDTH, ΔΛ0	SPATIAL SAMPLIN DISTANCE (SSD)	5
VIS 0.4	0.444 µm	0.060 µm	1.0 km	
VIS 0.5	0.510 µm	0.040 µm [TBC]	1.0 km	
VIS 0.6	0.640 µm [TBC]	0.050 µm [TBC]	1.0 km; 0.5 km*	
VIS 0.8	0.865 µm [TBC]	0.040 µm [TBC]	1.0 km	
VIS 0.9	0.914 µm [TBC]	0.020 µm [TBC]	1.0 km	
NIR 1.3	1.380 µm [TBC]	0.030 µm [TBC]	1.0 km	
NIR 1.6	1.610 µm	0.050 µm	1.0 km	
NIR 2.2	2.250 µm [TBC]	0.050 µm [TBC]	1.0 km; 0.5 km*	450 K MWIR
IR 3.8 (TIR)	3.800 µm	0.400 µm	2.0 km; 1.0 km*	channel
WV 6.3	6.300 µm	1.000 µm	2.0 km	channel
WV 7.3	7.350 µm	0.500 µm	2.0 km	
IR 8.7 (TIR)	8.700 µm	0.400 µm	2.0 km	
IR 9.7 (O ₃)	9.660 µm	0.300 µm	2.0 km	
IR 10.5 (TIR)	10.500 µm	0.700 µm	2.0 km; 1.0 km*	
IR 12.3 (TIR)	12.300 µm	0.500 µm	2.0 km	
IR 13.3 (CO ₂)	13.300 µm	0.600 µm	2.0 km	

Sentinel 3 – Sea & Land Surface Temperature Radiometer (SLSTR)

PRELIMINAY RESULTS (Nadir View)



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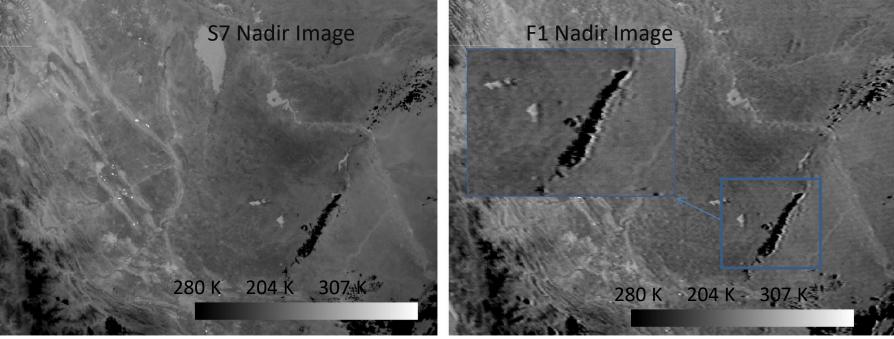


S7 vs. F1 Channel Noise

("Warm" ambient scene)



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Warm BT scene

- F1 image still seems noisier than S7 but less so than for prior colder scene. (expected due to NEdT being lower at higher temperatures)
- Odd "warm" BT shadow adjacent to some cold features e.g. clouds. (see zoom box above around cloud). Further examined next....

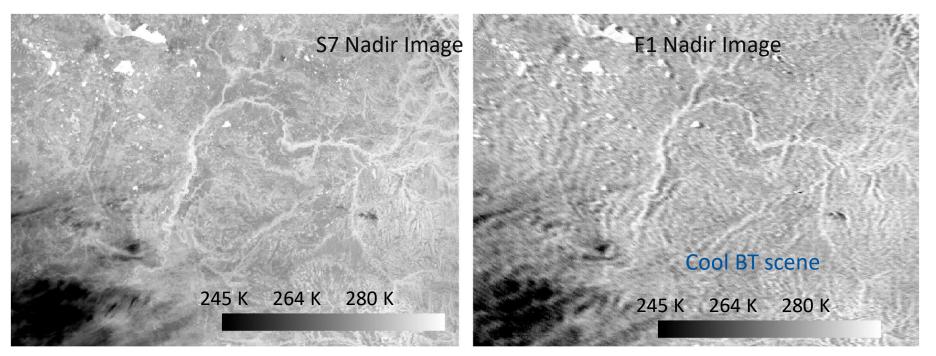
S3A_SL_1_RBT____20160528T184810_20160528T185110_20160530T151403_01 80_004_327_6599_LN2_O_NT_001.SEN3

S7 vs. F1 Channel Noise

("Cold" ambient scene)



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- F1 image has increased noise compared to S7 image. (expected due to much lower gain and wider dynamic range)
- Same type of difference not seen between F2 and S8.
- Applications should ideally use S7 for BT < 305 K and F1 > 305 K. (but not so easy to swap on pixel-by-pixel basis as area covered is different)

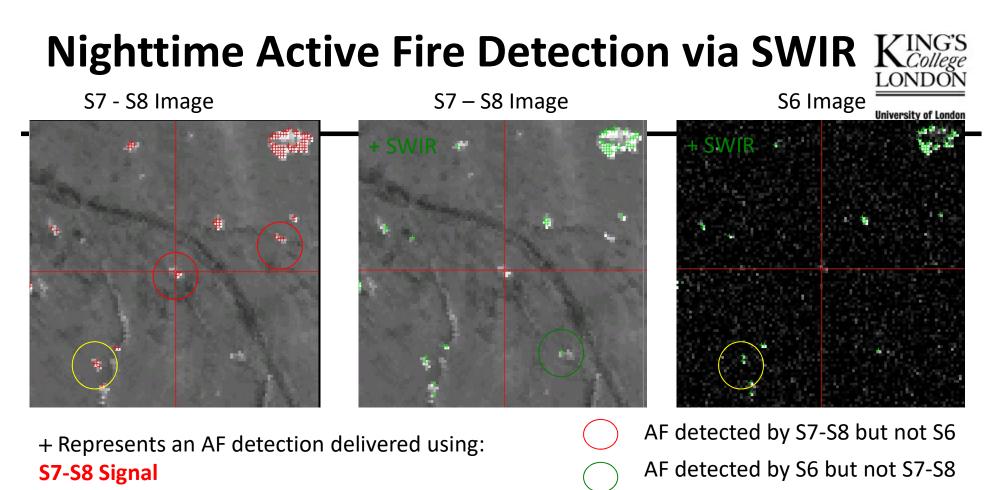


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S3A SL 1 RBT 2016052 8T184810 20160528T18511 0 20160530T151403 0180 Sentinel-3 SLSTR 004_327_6599_LN2_O_NT_ 001.SEN3 Active Fire: Fire Detection and Fire Here flares are **Radiative Power Assessment** apparent in S7 band (also seen in F1). Algorithm Theoretical Basis Document it position between S7 RSE-08230; No of Pages 19 Remote Sensing of Environment xxx (2012) xxx-xxx Contents lists available at SciVerse ScienceDirect **Remote Sensing of Environment** journal homepage: www.elsevier.com/locate/rse Sentinel-3 SLSTR active fire detection and FRP product: Pre-launch algorithm devel-**Zoom of Flare Area** opment and performance evaluation using MODIS and ASTER datasets

M.J. Wooster ^{a,*}, W. Xu ^a, T. Nightingale ^b

^a King's College London, Environmental Monitoring and Modelling Research Group, Department of Geography, London WC2R 2LS, United Kingdom ^b RAL Space, Rutherford Appleton Laboratory, Harwell Science and Innovation Campus, Didcot OX11 0QX, United Kingdom



S6 Signal

Conclusions:

• SWIR S6 provides additional capability for night-time AF detection (due to 4x smaller pixel area and near-zero background signal compared to S7-S8)

AF detected by both S7-S8 & S6

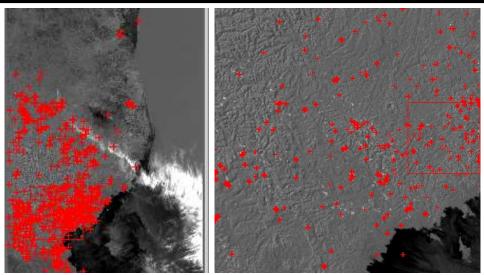
but non-identical AF pixels

- SWIR S6 detection is not sufficient to use a sole detection metric, and current ATBD test requires adjustment to add base threshold not just rely on L_{bck}+3 σ
- Update ATBD to detect AF pixels with S6 at full resolution, then identify the S7 pixel that the detection lies within and operate the alg. with that as a confirmed AF pixel.

Active Fire Detection Testing (Night-time)

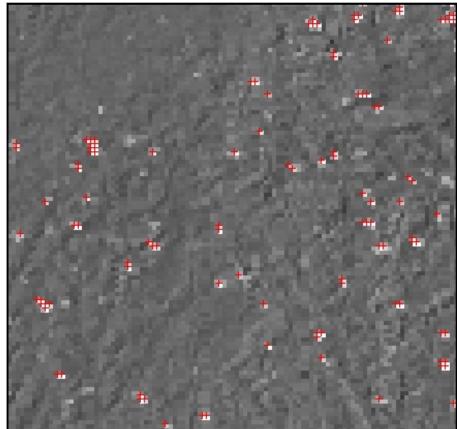


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Angola, Southern Africa.

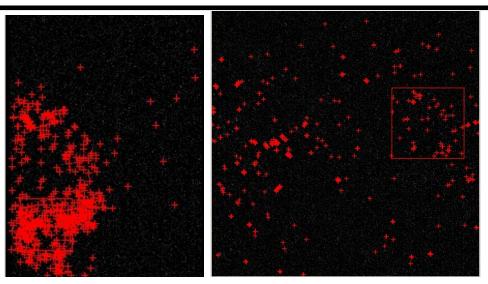
S7-S8 BT Difference from S3A-SLSTR @ 21:16 UTC on 03 Aug 2016 + SLSTR AF Pixels (S7-S8 detection)



Active Fire Detection Testing (Night-time)



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Angola, Southern Africa.

S6 Data from S3A-SLSTR @ 21:16 UTC on 03 Aug 2016 + SLSTR AF Pixels (S6 detection)

